Bounding the partition function of BCMP multiclass queueing networks

Jonatha Anselmi¹ and Paolo Cremonesi¹

¹Dipartimento of Elettronica e Informazione Politecnico di Milano

BWWQT 2009, Minsk

Jonatha Anselmi and Paolo Cremonesi Bounding the partition function of BCMP multiclass queueing network

▲□▶ ▲□▶ ▲□▶ ▲□▶ 三回日 のQ(~)

Outline



Motivation

- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations

▲□ ▶ ▲ ヨ ▶ ▲ ヨ ▶ ヨ 目 → の Q (~

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Outline



Motivation

- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

2 Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations



- Closed BCMP (Basket, Chandy, Muntz, Palacios, 1975) queueing networks have been widely adopted to analytically evaluate the performance of computer and communication systems,
- Extension of Gordon-Newell (1967) networks
- Jobs belong to multiple classes,
 - 2 more types of service disciplines,
 - more general service times probability distributions.

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Notation of a Closed BCMP Network



 $\rho_{ir} = e_{ir} / \mu_{ir}$: mean loading (service demand) of class-*r* jobs in station *i*

Motivation	
Our Result	
Summary	

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Main assumptions of Closed BCMP Networks

Per-class service time distributionFCFSExponential (with mean μ_{ir}^{-1} , and $\mu_1 = \cdots = \mu_R$)LCFS,PS,ISCoxian (with mean μ_{ir}^{-1})

Routing probabilities $p_{ij,r}$ are constants.

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Outline



Motivation

- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

2 Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Stationary Distribution of Closed BCMP Networks The complexity of the model

BCMP models are CTMC, and the stationary distribution is

$$G(\mathbf{N}) = \sum_{\mathbf{S}(\mathbf{N})} \prod_{i=1}^{M} \left(\sum_{r=1}^{R} n_{ir} \right)! \prod_{r=1}^{R} \frac{D_{ir}^{n_{ir}}}{n_{ir}!}$$
(1)
$$G(\mathbf{N}) = \sum_{\mathbf{S}(\mathbf{N})} \prod_{i=1}^{M} \left(\sum_{r=1}^{R} n_{ir} \right)! \prod_{r=1}^{R} \frac{D_{ir}^{n_{ir}}}{n_{ir}!}$$
(2)

$$\mathbf{S}(\mathbf{N}) = \left\{ n_{11}, \dots, n_{MR} : \sum_{i=1}^{M} n_{ir} = N_r, 1 \le r \le R \right\}.$$
 (3)

Then, the main problem is the computation of $G(\mathbf{N})$. In fact,

$$|\mathbf{S}(\mathbf{N})| = \prod_{r=1}^{R} \binom{N_r + M - 1}{M - 1}$$
(4)

 π

Bounding the partition function of BCMP multiclass queueing network

Motivation
Our Result
Summarv

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

Stationary Distribution of Closed BCMP Networks The complexity of the model

BCMP models are CTMC, and the stationary distribution is

 π

$$F(n_{11}, \dots, n_{MR}) = \frac{1}{G(\mathbf{N})} \prod_{i=1}^{M} \left(\sum_{r=1}^{R} n_{ir} \right)! \prod_{r=1}^{R} \frac{D_{ir}^{n_{ir}}}{n_{ir}!}$$
(1)
$$G(\mathbf{N}) = \sum_{\mathbf{S}(\mathbf{N})} \prod_{i=1}^{M} \left(\sum_{r=1}^{R} n_{ir} \right)! \prod_{r=1}^{R} \frac{D_{ir}^{n_{ir}}}{n_{ir}!}$$
(2)

$$\mathbf{S}(\mathbf{N}) = \left\{ n_{11}, \dots, n_{MR} : \sum_{i=1}^{M} n_{ir} = N_r, 1 \le r \le R \right\}.$$
 (3)

Then, the main problem is the computation of $G(\mathbf{N})$. In fact,

$$|\mathbf{S}(\mathbf{N})| = \prod_{r=1}^{R} \binom{N_r + M - 1}{M - 1}$$
(4)

BCMP Queueing Networks Difficulties of BCMP Queueing Networks

What are the solutions? A number of alternative analyses

Given that

 no (exact) polynomial algorithm is known for the solution of closed BCMP models,

alternative solutions are available:

- Bounding Analysis
- Asymptotic Analysis
- Approximate Analysis
- Bottleneck Analysis

Notivation	Hölder's Inequality
our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Outline



- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations

▲母 ▶ ▲ ヨ ▶ ▲ ヨ ▶ ヨ 目 = り へ ()



Hölder's Inequality in two dimensions

- Let *p* and *q* be positive real numbers such that 1/p + 1/q = 1.
- If S is a measurable subset on Rⁿ, and f₁ and f₂ are measurable real-valued functions on S, then

$$\int_{\mathcal{S}} \left| f_1(x) f_2(x) \right| \mathrm{d}x \le \left(\int_{\mathcal{S}} |f_1(x)|^p \, \mathrm{d}x \right)^{1/p} \left(\int_{\mathcal{S}} |f_2(x)|^q \, \mathrm{d}x \right)^{1/q}.$$
(5)

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Outline



- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations

Image: 1

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Our Objective

To apply the Hölder's Inequality (in the general case)

$$\int_{\mathcal{S}} \left| \prod_{r=1}^{R} f_r(x) \right| \mathrm{d}x \leq \prod_{r=1}^{R} \left(\int_{\mathcal{S}} |f_r(x)|^{p_r} \,\mathrm{d}x \right)^{1/p_r} \tag{6}$$

with $\sum_{r=1}^{R} 1/p_r = 1$, to the partition function of closed BCMP queueing networks

$$G(\mathbf{N}) = \sum_{\mathbf{S}(\mathbf{N})} \prod_{i=1}^{M} \left(\sum_{r=1}^{R} n_{ir} \right)! \prod_{r=1}^{R} \frac{D_{ir}^{n_{ir}}}{n_{ir}!}$$
(7)

to obtain a computationally efficient bound.

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Integral representation of $G(\mathbf{N})$

It is possible to show that

$$G(\mathbf{N}) = \frac{1}{\prod_{r=1}^{R} N_{r}!} \int_{\Re^{+M}} \prod_{r=1}^{R} H(r, \mathbf{u})^{N_{r}} e^{-(u_{1}+...+u_{M})} d\mathbf{u}$$
(8)

where $H(r, \mathbf{u}) = \rho_{0r} + \rho_{1r}u_1 + \cdots + \rho_{Mr}u_M$.

(8) can be rewritten as

$$G(\mathbf{N}) = \frac{1}{\prod_{r=1}^{R} N_r!} \int_{\Re^{+M}} \prod_{r=1}^{R} \left[H(r, \mathbf{u})^N e^{-(u_1 + \dots + u_M)} \right]^{\beta_r} d\mathbf{u}$$
(9)
where $\beta_r = N_r/N.$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ④ ●

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Integral representation of $G(\mathbf{N})$

It is possible to show that

$$G(\mathbf{N}) = \frac{1}{\prod_{r=1}^{R} N_{r}!} \int_{\Re^{+M}} \prod_{r=1}^{R} H(r, \mathbf{u})^{N_{r}} e^{-(u_{1}+...+u_{M})} d\mathbf{u}$$
(8)

where $H(r, \mathbf{u}) = \rho_{0r} + \rho_{1r}u_1 + \cdots + \rho_{Mr}u_M$.

• (8) can be rewritten as

$$G(\mathbf{N}) = \frac{1}{\prod_{r=1}^{R} N_{r}!} \int_{\Re^{+M}} \prod_{r=1}^{R} \left[H(r, \mathbf{u})^{N} e^{-(u_{1} + \dots + u_{M})} \right]^{\beta_{r}} d\mathbf{u}$$
(9)

where $\beta_r = N_r/N$.

Applying Hölder's result

Therefore, Hölder's inequality yields

$$G(\mathbf{N}) \leq \prod_{r=1}^{R} \frac{1}{N_{r}!} \left[\int_{\Re^{+M}} H(r, \mathbf{u})^{N} e^{-(u_{1}+\ldots+u_{M})} d\mathbf{u} \right]^{\beta_{r}} \quad (10)$$

• Now, multiplying and dividing by N!, we obtain

$$\boldsymbol{G}(\mathbf{N}) \leq N! \prod_{r=1}^{R} \frac{1}{N_r!} \left[\frac{1}{N!} \int_{\Re^{+M}} H(r, \mathbf{u})^N e^{-(u_1 + \ldots + u_M)} d\mathbf{u} \right]^{\beta_r}$$
(11)

 ⇒ the expression in the brackets can be interpreted as the integral representation of the partition function of a singleclass network populated by N class-r jobs only.

Applying Hölder's result

Therefore, Hölder's inequality yields

$$G(\mathbf{N}) \leq \prod_{r=1}^{R} \frac{1}{N_r!} \left[\int_{\Re^{+M}} H(r, \mathbf{u})^N e^{-(u_1 + \ldots + u_M)} d\mathbf{u} \right]^{\beta_r} \quad (10)$$

• Now, multiplying and dividing by N!, we obtain

$$G(\mathbf{N}) \leq N! \prod_{r=1}^{R} \frac{1}{N_r!} \left[\frac{1}{N!} \int_{\Re^{+M}} H(r, \mathbf{u})^N e^{-(u_1 + \dots + u_M)} d\mathbf{u} \right]^{\beta_r}$$
(11)

 ⇒ the expression in the brackets can be interpreted as the integral representation of the partition function of a singleclass network populated by N class-r jobs only.

Applying Hölder's result

Therefore, Hölder's inequality yields

$$G(\mathbf{N}) \leq \prod_{r=1}^{R} \frac{1}{N_r!} \left[\int_{\Re^{+M}} H(r, \mathbf{u})^N e^{-(u_1 + \ldots + u_M)} d\mathbf{u} \right]^{\beta_r} \quad (10)$$

• Now, multiplying and dividing by N!, we obtain

$$G(\mathbf{N}) \leq N! \prod_{r=1}^{R} \frac{1}{N_r!} \left[\frac{1}{N!} \int_{\Re^{+M}} H(r, \mathbf{u})^N e^{-(u_1 + \ldots + u_M)} d\mathbf{u} \right]^{\beta_r}$$
(11)

 → the expression in the brackets can be interpreted as the integral representation of the partition function of a singleclass network populated by N class-r jobs only.

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Main Result

• Hence,

$$G(\mathbf{N}) \leq \prod_{r=1}^{R} \frac{[N!G(N\mathbf{e}_{r})]^{\beta_{r}}}{N_{r}!} = \binom{N}{N_{1}, \dots, N_{R}} \prod_{r=1}^{R} G(N\mathbf{e}_{r})^{\beta_{r}}$$
(12)

where \mathbf{e}_r is the unit vector in direction r.

 → the upper bound on the partition function of a closed, multiclass BCMP queueing network is provided.

Notes on $G(N\mathbf{e}_r)$

 $G(Ne_r)$ refers to a single-class queueing network. Therefore,

- it can be computed efficiently
 - The computational complexity of the MVA is O(MN)
 - The computational complexity of Koenigsberg's formula is O(M²))
- Koenigsberg's formula provides the asymptotic behavior

$$G(N\mathbf{e}_r) \approx \frac{(\max_{i \ge 1} \rho_{ir})^{N+M-1}}{\prod_{j=1, j \neq \arg\max_{i \ge 1} \rho_{jr}}^{M} (\max_{i \ge 1} \rho_{ir} - \rho_{jr})}$$
(13)

i.e., the order of magnitude of $G(Ne_r)$.

Notes on $G(N\mathbf{e}_r)$

 $G(Ne_r)$ refers to a single-class queueing network. Therefore,

- it can be computed efficiently
 - The computational complexity of the MVA is O(MN)
 - The computational complexity of Koenigsberg's formula is O(M²))
- Koenigsberg's formula provides the asymptotic behavior

$$G(N\mathbf{e}_r) \approx \frac{(\max_{i \ge 1} \rho_{ir})^{N+M-1}}{\prod_{j=1, j \neq \arg\max_{i \ge 1} \rho_{jr}}^{M} (\max_{i \ge 1} \rho_{ir} - \rho_{jr})}$$
(13)

i.e., the order of magnitude of $G(Ne_r)$.

Motivation	Hölder's Inequality
Our Result	Bounding the Partition Function
Summary	Load-Dependent Stations

Outline



- BCMP Queueing Networks
- Difficulties of BCMP Queueing Networks

Our Result

- Hölder's Inequality
- Bounding the Partition Function
- Load-Dependent Stations

Image: 1

▲母 ▶ ▲ ヨ ▶ ▲ ヨ ▶ ヨ 目 = り へ ()

Extension to LD Stations

- Load-Dependent (LS) station: service rates μ_{ir} are multiplied by queue-lenght functions, i.e., x_i(n) or y_{ir}(n).
- Making the following replacements

$$\rho_{ir} \leftarrow \begin{cases} \rho_{ir} / \inf_n x_i(n) \\ \rho_{ir} / \inf_n y_{ir}(n) \end{cases}$$
(14)

the resulting queueing network is composed of only LI stations and the new value of the partition function bounds from above the original one, and

• Bound (12) can be applied again.

Extension to LD Stations

- Load-Dependent (LS) station: service rates μ_{ir} are multiplied by queue-lenght functions, i.e., x_i(n) or y_{ir}(n).
- Making the following replacements

$$\rho_{ir} \leftarrow \begin{cases} \rho_{ir} / \inf_n x_i(n) \\ \rho_{ir} / \inf_n y_{ir}(n) \end{cases}$$
(14)

the resulting queueing network is composed of only LI stations and the new value of the partition function bounds from above the original one, and

• Bound (12) can be applied again.



- We proposed a new inequality upper bounding the partition function of multiclass, closed BCMP queueing networks in terms of *R* partition functions related to single-class, closed BCMP queueing networks,
- The upper bound can be computed efficiently,
- Beyond the theoretical interest, it can provide an estimate of the minimum amount of memory that exact solution algorithms implementations should allocate to avoid numerical instabilities.



- We proposed a new inequality upper bounding the partition function of multiclass, closed BCMP queueing networks in terms of *R* partition functions related to single-class, closed BCMP queueing networks,
- The upper bound can be computed efficiently,
- Beyond the theoretical interest, it can provide an estimate of the minimum amount of memory that exact solution algorithms implementations should allocate to avoid numerical instabilities.



- We proposed a new inequality upper bounding the partition function of multiclass, closed BCMP queueing networks in terms of *R* partition functions related to single-class, closed BCMP queueing networks,
- The upper bound can be computed efficiently,
- Beyond the theoretical interest, it can provide an estimate of the minimum amount of memory that exact solution algorithms implementations should allocate to avoid numerical instabilities.

For Further Reading I



🦠 Jonatha Anselmi.

New Analyses in BCMP Queueing Networks Theory. PhD Thesis, March 2009. Politecnico di Milano, Italy